

The phase transition in Achlioptas processes

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 - Definitions
 - Results
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The Erdős–Rényi random graph process

Fix a set V of n vertices (usually $V = [n] = \{1, 2, \dots, n\}$).

Define a random sequence (G_m) , $m = 0, 1, \dots, \binom{n}{2}$, of graphs on V as follows:

- G_0 has no edges.
- Given G_0, \dots, G_{m-1} , pick e_m uniformly at random from all edges not present in G_{m-1} .
- Set $G_m = G_{m-1} + e_m$.

Note G_m has m edges and the distribution of $G_{n,m}$.

Erdős–Rényi phase transition

Classical result of Erdős and Rényi (1960).

Let $L_1(G)$ denote the number of vertices in the largest component of G .

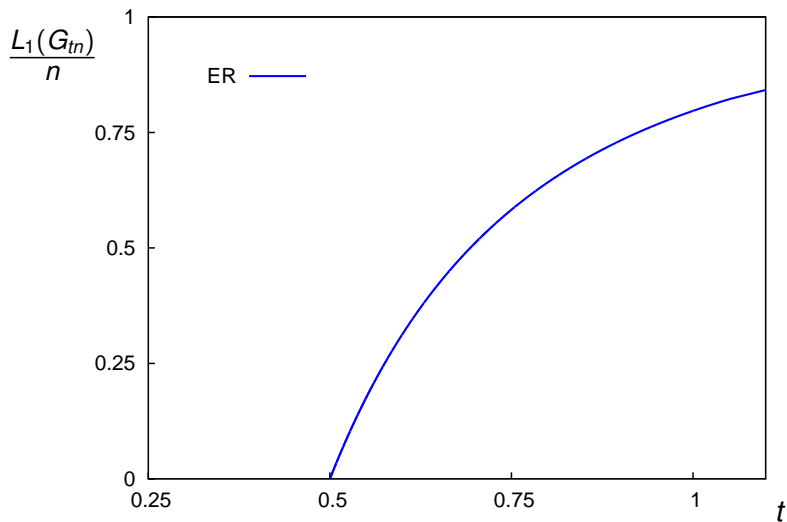
Theorem

Let t be a constant, and let $G = G_{n,tn}$. (Ignore rounding.)

- If $t < 1/2$ then \exists constant $A(t) > 0$ such that $L_1(G) \leq A(t) \log n$ whp (with high probability).
- If $t > 1/2$ then \exists constant $\rho(t)$ such that $L_1(G)/n \xrightarrow{P} \rho(t)$.
- If $t = 1/2$ then $L_1(G)$ is of order $n^{2/3}$ whp.

They gave formulae for the constants, and proved more.

Erdős–Rényi scaling limit



Where next?

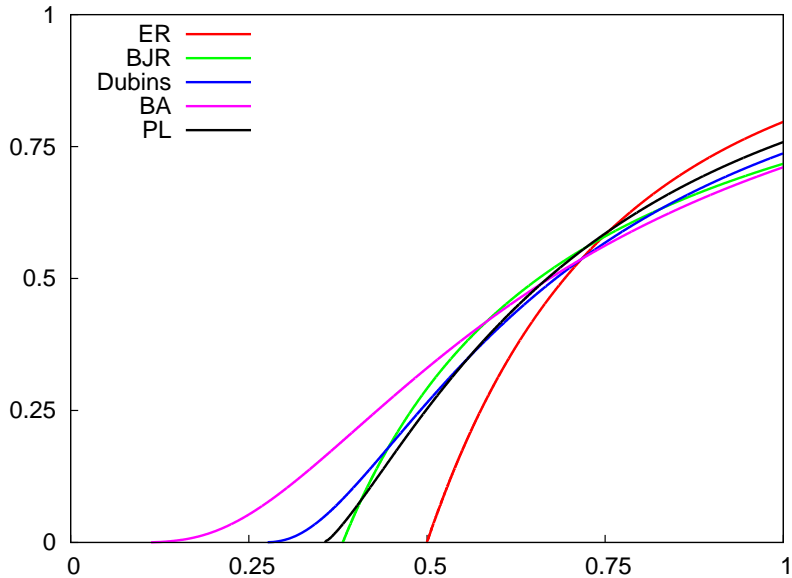
Two directions from here:

- Investigate this model in more detail.
- Investigate this phenomenon in other models.

Phase transitions in other models

- Random subgraphs of hypercubes. [Ajtai, Komlós, Szemerédi, 1982](#)
- Random subgraphs of r -regular graphs. [Goerd, 2001](#)
- Bollobás's **configuration model**: [Molloy, Reed, 1995, 1998](#)
scale-free case: [Chung, Lu, 2000/1](#)
- Barabási–Albert model. [Bollobás, R., 2003](#)
- Uniformly grown (CHKNS/Dubins) model. [Durrett, 2003](#),
[Bollobás, Janson, R., 2005](#)
- BJR model [Bollobás, Janson, R., 2007](#)
- (Classical percolation: Hammersley, Harris, Kesten, ...)

Various BJR scaling limits



Power of two random choices

Suppose we have n (or $\Theta(n)$) balls to place into n bins.
(Corresponding e.g., to hashing, or task allocation.)

Random choice: fairly uniform, but still $\log n / \log \log n$ balls in some bin.

For each ball, choose **two** random bins, put ball in least full.
Then **much** more uniform: at most $\log \log n$ balls in any bin.

[Azar, Broder, Karlin, Upfal, 1994, 1999](#)

In 2000 Achlioptas asked: can two choices affect the ER random graph process?

Can it delay/accelerate the phase transition?

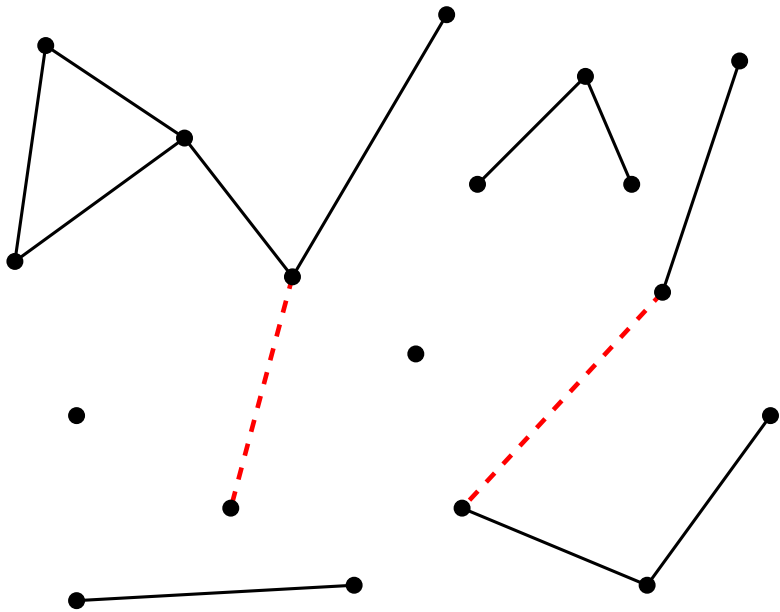
Semi-formal definition

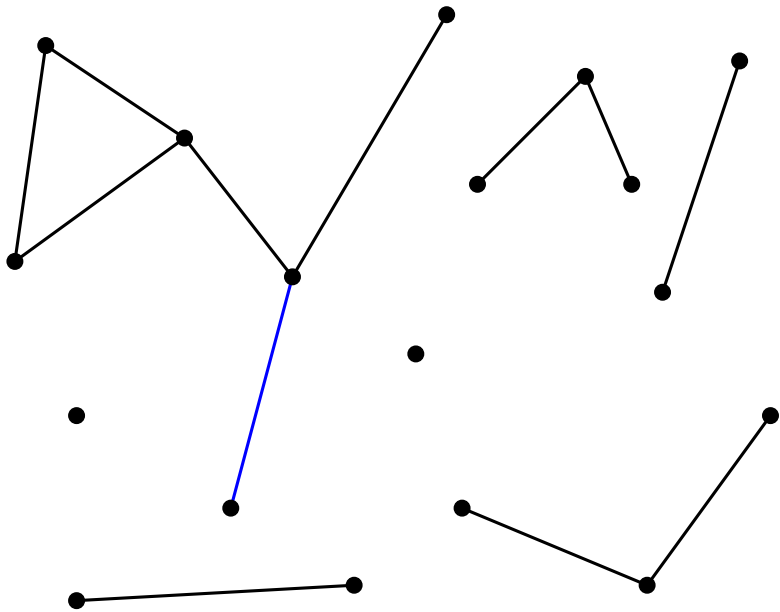
Let \mathcal{R} be a 'decision rule'.

Let V be a set of n vertices. The **Achlioptas process**

$(G_m)_{m \geq 0} = (G_{n,m}^{\mathcal{R}})_{m \geq 0}$ is defined as follows:

- G_0 is the graph on V with no edges.
- Given G_0, \dots, G_{m-1} , let e_m^1 and e_m^2 be two possible edges chosen uniformly at random (independently).
- Select one of the edges according to rule \mathcal{R} .
- Then $G_m = G_{m-1} + e_m^1$ or $G_{m-1} + e_m^2$.





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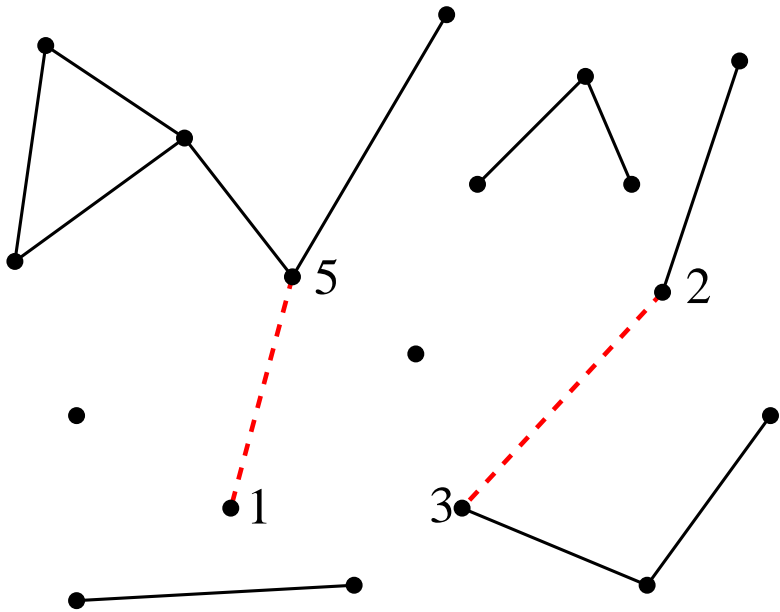
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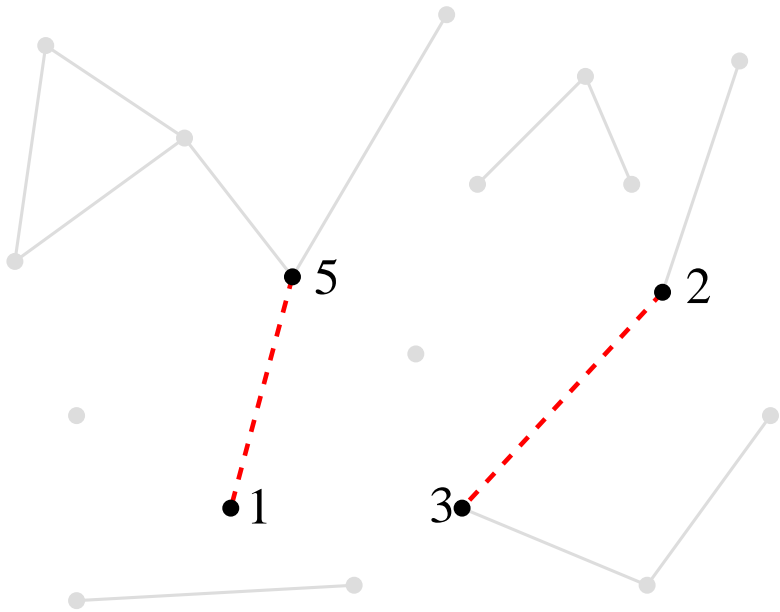
- G_0 is the graph on V with no edges.
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- Select one of the edges according to rule \mathcal{R} .
- Then $G_m = G_{m-1} + e_m^1$ or $G_{m-1} + e_m^2$.

Minor variants: select from edges not present/not previously selected. Or select random vertices. Here, no significant difference.

Classes of rules (more to less general):

- **General**: decision based on any information about past+present (i.e., $(e_k^i)_{k \leq m, i=1,2}$ - in particular on G_{m-1} as labelled graph).
- **Size rules**: decision based only on sizes of components involved.





Classes of rules (more to less general):

- **General**: decision based on any information about past+present (i.e., $(e_k^i)_{k \leq m, i=1,2}$ - in particular on G_{m-1} as labelled graph).
- **Size rules**: decision based only on sizes of components involved.
- **Bounded size rules**: as above, but for constant B all sizes $> B$ treated same.

Most of the time only size rules considered. Bounded size easier to analyze.

Which rule?

How to accelerate/delay phase transition?

A key statistic is the **susceptibility**:

$$\chi(G) = \frac{1}{n} \sum_i |C_i|^2.$$

If we join components of sizes a and b , $\Delta\chi(G) \propto ab$.

Bollobás suggested **product rule** should be best.

Earlier phase transition

With hindsight, trivial to produce transition before $t = 0.5$.

E.g., let $U \subset V$ with $|U| = 0.99n$, and select edges within U when possible.

Edges are added to U at rate > 0.999 , so Erdős–Rényi result gives giant by $m = (0.5n * 0.99)/0.999 < 0.5n$.

In general ‘inhomogeneous’ (but ‘blind’) rules give earlier transition.

Isolated vertex rules

Bohman and Frieze (2001) found a rule \mathcal{R} for which they could prove $t_c > 0.5$. (In fact $t_c > 0.535$).

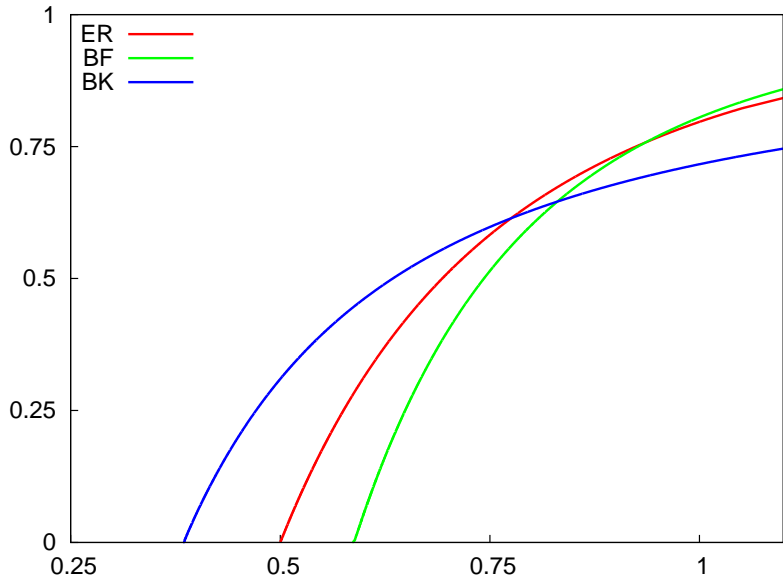
Essentially: 'select e_m^1 if both ends isolated, otherwise e_m^2 '.

A bounded size rule, with $B = 1$.

Bohman and Kravitz (2006) proved $t_c < 0.385$ for the size rule 'select e_m^1 if nether end isolated, otherwise e_m^2 '.

They also analyzed other 'bounded first-edge size rules'.

Some scaling limits



Each size rule \mathcal{R} suggests a system of differential equations:

$$\rho'_k(t) = \sum_{a,b,c,d} \Delta_{k,a,b,c,d} \rho_a(t)\rho_b(t)\rho_c(t)\rho_d(t)$$

with $\Delta_{k,a,b,c,d} \in \{-2k, -k, 0, k\}$ depending on \mathcal{R} .

Spencer and Wormald 2007: for **bounded** size rules, the **small** components behave as the DEs predict.

Also, t_c (point when giant appears) given by the blow-up point of the system of DEs.

Janson and Spencer 2012: found rate of emergence of giant for Bohman–Frieze process.

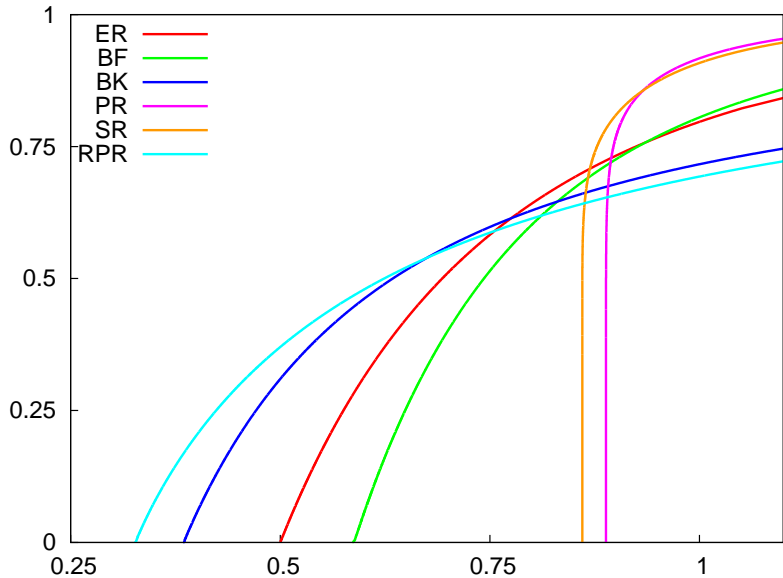
Questions

Even for **bounded** size rules, does scaling limit exist?

Are all vertices not in small components in a unique giant?

What about non-bounded case, e.g., Bollobás's product rule?

More scaling limits



Explosive percolation

Conjecture (Achlioptas, D'Souza, Spencer 2009)

The product rule has a discontinuous transition!

More precisely, $L_1(G_m)$ grows from $< n^{1/2}$ to $> 0.5n$ in $< 2n^{2/3}$ steps.

Based on 'conclusive' numerical evidence.

Called **explosive** percolation.

Very exciting - many citations in physics literature.

Heuristic support from many physicists. But not all: [da Costa](#), [Dorogovtsev](#), [Goltsev](#), [Mendes 2010](#)

Theorem (R., Warnke 2011)

Every Achlioptas process has a continuous phase transition.

Theorem (R., Warnke 2011)

In any Achlioptas process, almost all vertices not in small components are in a unique giant.

Analogue of Erdős–Rényi sprinkling argument.

Corollary

If small components ‘behave’, scaling limit exists. In particular, all bounded size rules have a scaling limit.

Convergence questions

Does the product rule have a scaling limit? Perhaps **all** size rules do?

Theorem (R., Warnke 2013+)

Small components behave at least until the point where $\chi(G_m)$ diverges.

Probably, this point is t_c .

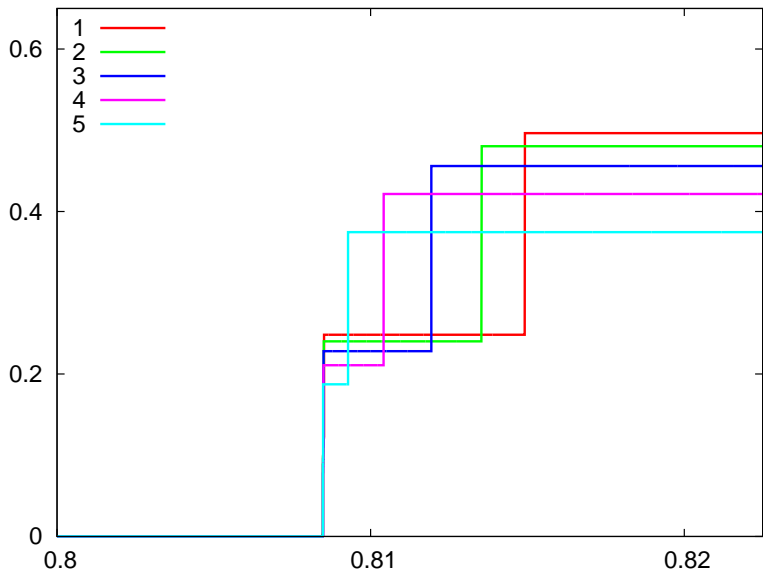
Theorem (R., Warnke 2013+)

*Yes (modulo natural condition) **if** a corresponding system of differential equations has a unique solution.*

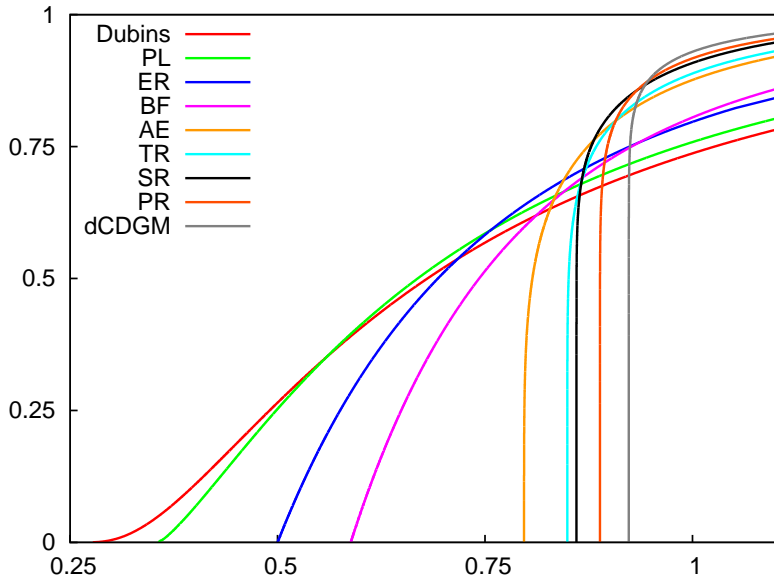
NB. System of DEs includes term for giant component.

'Direct' proof - not via standard DE method.

A warning!



What is happening?



What is happening?

For a class of unbounded size rules, the phase transition appears to be **extremely** steep.

Can we show $\rho'(t_c) = \infty$?

Can we give sensible upper bounds? R-W result gives $\rho(t_c + \varepsilon) \leq 1/(\log \log(1/\varepsilon))^C$.

Physicists expect $\rho(t_c + \varepsilon) = \Theta(\varepsilon^\beta)$. Perhaps $\beta = 1/18$ for dCDGM rule.

Can we examine the scaling window, say for bounded size rules?

- Bhamidi, Budhiraja, Wang
- Kang, Perkins, Spencer

What about other explosive processes?

- Panagiotou, Spöhel, Steger, Thomas 2013
- Cho, Hwang, Herrmann, Kahng 2013