# Galton-Watson Trees in Statistical Alignment 

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## Outline

(9) Galton Watson Trees
(2) Insertion-Deletion Models
(3) Multiple Alignments

4 Challenges/Problems: Bayesian Sampling of Multiple Alignments

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2 Insertion-Deletion Models
(3) Multiple Alignments
(4) Challenges/Problems: Bayesian Sampling of Multiple Alignments

## Galton and Watson

## Sir Francis Galton 1822-1911

Henry William Watson
1827-1903


## Galton and Watson

## Sir Francis Galton 1822-1911

Henry William Watson<br>1827-1903

What's the probability for an English aristocratic family name to die out?

## Galton Watson Tree

$$
t=0
$$

$X_{k}:=$ number of offsprings at node $k$
$X_{1}, X_{2}, X_{3}, \ldots$ i.i.d. random variables

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variables

## Galton Watson Tree

$$
\begin{aligned}
& t=0 \\
& t=1 \\
& t=2 \\
& t=3 \\
& t=4 \\
& t=5
\end{aligned}
$$ $X_{1}, X_{2}, X_{3}, \ldots$ i.i.d. random

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variables

## Galton Watson Tree



| $\mathrm{t}=0$ |  |
| :---: | :---: |
| $t=1$ |  |
| $\mathrm{t}=2$ |  |
| $\mathrm{t}=3$ | $X_{k}:=$ number of offsprings at node $k$ |
|  | $X_{1}, X_{2}, X_{3}, \ldots$ i.i.d. random |
| $t=5$ | variables |
| $\mathrm{t}=6$ |  |
| $\mathrm{t}=7$ |  |
| $\mathrm{t}=8$ |  |

## Galton Watson Tree



| $\mathrm{t}=0$ |  |
| :--- | :--- |
| $\mathrm{t}=1$ |  |
| $\mathrm{t}=2$ |  |
| $\mathrm{t}=3$ | $X_{k}:=$ number of offsprings |
| $\mathrm{t}=4$ | at node $k$ |
|  | $X_{1}, X_{2}, X_{3}, \ldots$ i.i.d. random |
| $\mathrm{t}=5$ | variables |
| $\mathrm{t}=6$ | $\mathbb{E} X_{k}<1:$ "subcritical" |
| $\mathrm{t}=7$ | $\mathbb{E} X_{k}=1:$ "critical" |
| $\mathbb{E} X_{k}>1:$ "supercritical" |  |
| $\mathrm{t}=8$ |  |
| $\mathrm{t}=9$ |  |

## Galton-Watson Process in continuous time



Time

## Binary Branching GW Process in cont. time



Time

## Theorem

If a Galton-Watson process with binary branching or geometric offspring distribution (on $\{0,1,2, \ldots\}$ ) is still alive at time $t$, then the number of survivors at time $t$ is geometrically distributed (on $\{1,2,3, \ldots\})$.

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on $\{0,1,2, \ldots\}: \operatorname{Pr}(X=k)=(1-p)^{k} \cdot p$

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```
on {0,1,2,\ldots}:}\operatorname{Pr}(X=k)=(1-p\mp@subsup{)}{}{k}\cdot
on {1,2,\ldots}:
    Pr}(X=k)=(1-p\mp@subsup{)}{}{k-1}\cdot
```


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\begin{array}{ll}
\text { on }\{0,1,2, \ldots\}: & \operatorname{Pr}(X=k)=(1-p)^{k} \cdot p, \mathbb{E}(X)=(1-p) / p \\
\text { on }\{1,2, \ldots\}: & \operatorname{Pr}(X=k)=(1-p)^{k-1} \cdot p
\end{array}
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\end{array}
$$

The geometric distribution is the only one on $\{(0) 1,2,3,, \ldots\}$ without memory: $\operatorname{Pr}(X=n+k \mid X>n)=\operatorname{Pr}(X=k)$

## Outline

## (4) Galton Watson Trees

(2) Insertion-Deletion Models

3 Multiple Alignments
4) Challenges/Problems: Bayesian Sampling of Multiple Alignments

## Model of Sequence Evolution

Thorne, Kishino, Felsenstein (1991):
Deletions with rate $\mu$ at each site.
Insertions with rate $\lambda$ right of each site \& at the very left.
Substitutions with Rate $s$ at each site.


TKF alignment convention:
like this:


## Reversibility?



## Consequence of TKF convention

## The bare alignment

$\mathrm{BBBB} \_\mathrm{BB} \_\mathrm{BB}$
B_BBB_BB_BB
is generated by a Markov chain:


## Consequence of TKF convention

## The bare alignment

$\mathrm{BBBB} \_\mathrm{BB} \_\mathrm{BB}$
B_BBB_BB_BB
is generated by a Markov chain:


| from $\backslash$ to | ${ }^{\mathrm{B}}$ | B | $\overline{\mathrm{B}}$ |
| :---: | :---: | :---: | :---: |
| ${ }_{\mathrm{B}}^{\mathrm{B}}$ | $(1-\lambda \beta) \frac{\lambda}{\mu} e^{-\mu}$ | $(1-\lambda \beta) \frac{\lambda}{\mu}\left(1-e^{-\mu}\right)$ | $\lambda \beta$ |
| ${ }_{\mathrm{B}}$ | $\lambda \beta \frac{e^{-\mu}}{1-e^{-\mu}}$ | $\lambda \beta$ | $\frac{1-e^{-\mu}-\mu \beta}{1-e^{-\mu}}$ |
| - | $(1-\lambda \beta) \frac{\lambda}{\mu} e^{-\mu}$ | $(1-\lambda \beta) \frac{\lambda}{\mu}\left(1-e^{-\mu}\right)$ | $\lambda \beta$ |

transition probabilies im (model: TKF'91), $\beta=\frac{1-e^{\lambda-\mu}}{\mu-\lambda e^{\lambda-\mu}}$

The Markov chain (the alignment) is hidden, observable is the pair of sequences emitted by the alignment.

pair Hidden Markov Model (pair HMM)

## Why Markov?



## Why Geometric Distribution?



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## Computing transition probabilies

Simplification: $\lambda=\mu$

$X:=$ number of survivors at time $t$

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\mathbb{E}(X)=1
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& \mathbb{E}(X)=1 \\
& \operatorname{Pr}(X=k \mid X>0)= \\
& (1-p)^{k-1} \cdot p
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& \frac{1}{p}=\mathbb{E}(X \mid X>0)=1+t \cdot \lambda
\end{aligned}
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& \\
& \begin{aligned}
1= & \mathbb{E}(X) \\
= & \operatorname{Pr}(X=0) \cdot \mathbb{E}(X \mid X=0) \\
& \quad+\operatorname{Pr}(X>0) \cdot \mathbb{E}(X \mid X>0)
\end{aligned}
\end{aligned}
$$

$X:=$ number of survivors at time $t$

## Computing transition probabilies

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& +\operatorname{Pr}(X>0) \cdot \mathbb{E}(X \mid X>0) \\
& =\operatorname{Pr}(X>0) \cdot(1+t \cdot \lambda) \\
& \Rightarrow \quad \operatorname{Pr}(X>0)=1 /(1+t \cdot \lambda)
\end{aligned}
$$

$X:=$ number of survivors at time $t$

## InDels are usually longer than 1 position


J.L. Thorne, H. Kishino, J. Felsenstein (1992) Inching towards reality: an improved likelihood model for sequence evolution. J. Mol. Evol., 34, 3-16.
D. Metzler (2003) Statistical alignment based on fragment insertion and deletion models, Bioinformatics 19:490-499.

FID Model (also a pairHMM):

- instead of single nucleotides, fragments are inserted an deleted with rate $\lambda$.
- Length of the fragments: geometrically distributed, mean length: $\gamma$.

$$
\operatorname{Pr}(L=k)=\frac{1}{\gamma}\left(1-\frac{1}{\gamma}\right)^{k}
$$

forbidden in TKF92 and FID:


GID Model:

- $\uparrow$ this is allowed
- no hidden Markov structure

Use GID to simulate data and test robustness of FID

How good are FID-based methods when GID/"Long Indel Model" is true?

- no problem for parameter estimations (Metzler, 2003)
- alignment accuracy can be decreased (Miklos, Lunter, Holmes, 2004)

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Maybe generate mixed-geometric gap-length with different types of fragments.

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Maybe generate mixed-geometric gap-length with different types of fragments.
Along a tree fragmentation may change from edge to edge.

## InDel Model for detecting conserved regions

A. Arribas-Gil, D. Metzler, J.-L. Plouhinec (2007)

| slow | fast TKF92 |  |  | slow |  | fast TKF92 |  |  |  | slow | fast TKF92 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | BB | BBBB | B | BBBB | BBB | B | BBBB | BB | BBBB | BBBBBBBBB | BBB | BBB |

## Outline

## (1) Galton Watson Trees <br> Insertion-Deletion Models

(3) Multiple Alignments
4) Challenges/Problems: Bayesian Sampling of Multiple Alignments
I. Holmes, W. J. Bruno (2001) Evolutionary HMMs: a Bayesian approach to multiple alignment, Bioinformatics 17:803-820.
R. Fleißner, D. Metzler, A. von Haeseler (2005) Simultaneous statistical multiple alignment and phylogeny reconstruction. Systematic Biology 54(4):548-61.


## multiple HMM for sampling a sequence given its neighbours


G.A. Lunter, I. Miklós, Y.S. Song, J. Hein (2003) An efficient algorithm for statistical multiple alignment on arbitrary phylogenetic trees. J. Comp. Biol. 10(6):869-889.





Tree-Indexed Heirs Line $=$ : TIHL



A

A


A
A

A
$\mathbf{A}$
-


A -
A C
-


A
AC

A -
A C


A $-G$
A $C G$
$-\quad-T$


A $-\mathbf{G}$
A C G
$-\quad-\mathbf{T}$

$\mathbf{A}-\mathbf{G} \mathbf{A}$
$\mathbf{A C G -}$
$-\quad \mathbf{T}-$


A G
ACG
TA

A-GA
AC G-
_ - T -


A G
ACG
TA

A-GA
AC G -
_ - T -


A-GA
AC G-

-     - T -


A-GAA-
ACG-A-
_ - T - - T


AGA
ACGA
TAT

A-GAA-
ACG-A-

-     - T- - T


A-GAA_T
ACG-A -
_ - T- - T -


AGAT
ACGA
TAT
$A_{-} G A A_{-} T$
ACG-A--

-     - T- $\mathbf{T}$ -

TKF91: states of hidden Markov chain are the Sets Of Active Nodes (soans).

$$
P_{\mathcal{S}}(k)=\sum_{(\mathcal{R}, e): \mathcal{S}=[\mathcal{R}, e]} p(e) q(e) P_{\mathcal{R}}\left(k-v_{e}\right) \vartheta(e, k)
$$

where
$k$ : Multi-index of Positions in sequences at leaves
$\mathcal{S}=[\mathcal{R}, e] \quad: \quad$ tihl $e$ turns soan $\mathcal{S}$ into soan $\mathcal{R}$
$P_{\mathcal{S}}(k)$ : $\operatorname{Pr}$ (sequences up to $k$ are generated and end there)
$p(e)=\operatorname{Pr}($ indel history of $e)$
$q(e)=\operatorname{Pr}($ no inserts at nodes in $e)$
$\vartheta(e, k)=\operatorname{Pr}(e$ emits base given in data types at $k)$
$v_{e} \in\{0,1\}^{n} \quad: \quad$ indicates postions in leaf-sequences to which $e$ emi

TKF91: states of hidden Markov chain are the Sets Of Active Nodes (soans).

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Transfer this to FID or TKF92 (fragmentation may change from edge to edge)

- D. Metzler, R. Fleißner, A. Wakolbinger, A. von Haeseler (2005) Stochastic insertion-deletion processes and statistical sequence alignment.
- D. Metzler, R. Fleißner (2007) Sequence Evolution Models for Simultaneous Alignment and Phylogeny Reconstruction.
state space: edge-labellings with $\{B, H, e, b, h\}$.

tihl $=$ tree indexed heirs line
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tihl $=$ tree indexed heirs line

Example: 3-leaved tree
TKF91: $2^{3}=8$ possible sets of active nodes
TKF92/FID: $5^{3}=125$ possible labellings, 41 of them are relevant

## Outline



## Galton Watson Trees

 <br> Insertion-Deletion Models}(3) Multiple Alignments

4 Challenges/Problems: Bayesian Sampling of Multiple Alignments


- re-sample alignments of 3-star subtrees (like J.L. Jensen and J. Hein, 2005, do for TKF91)
- do this only for limited parts of the sequences
- Can non-emitting tihls be ignored?
- assing sequences to internal nodes or use nucleotide (or AA) distributions?

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When changing the tree topology...


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...keep alignments of exterior sequences fixed.
(TKF91: 32 SOANS; FID: 437 relevant labellings)

## Conclusions

- We need multiple-alignment sampling to assess the full uncertainty in phylogeny estimation
- Let's write the software and try if it works! - THANK YOU!


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